

# Mini-course on Epistemic Game Theory

## Lecture 3: Backward Induction Reasoning

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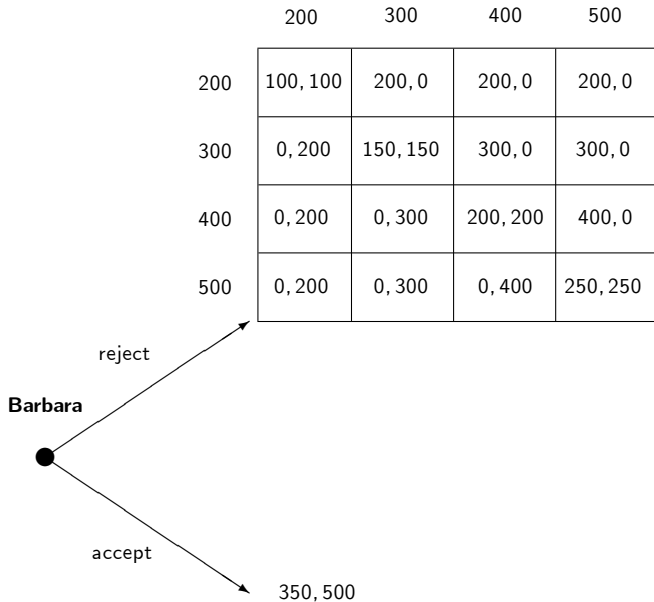
Maastricht University

Toulouse, June/July 2015

- In a **dynamic game**, players may choose one after the other.
- Before you make a choice, you may (partially) observe what your opponents have chosen so far.
- It may happen that your **initial belief** about the opponents' choices will be **contradicted** later on.
- Then you must **revise** your belief about the opponents' choices. **But how?**
- There may be **several plausible** ways to revise your belief.

## Story

- Chris is planning to paint his house tomorrow, and needs someone to help him.
- You and Barbara are both interested. This evening, both of you must come to Chris' house, and whisper a price in his ear. Price must be either 200, 300, 400 or 500 euros.
- Person with lowest price will get the job. In case of a tie, Chris will toss a coin.
- Before you leave for Chris' house, Barbara gets a phone call from a colleague, who asks her to repair his car tomorrow at a price of 350 euros.
- Barbara must decide whether or not to accept the colleague's offer.



	200	300	400	500
200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250

**Barbara**

reject

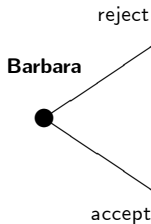


accept

350, 500

Initially, you believe that Barbara accepts the offer.  
 What if you observe that she has rejected the offer?  
 Then, you must revise your belief.  
 But how?

	200	300	400	500
200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250



**Backward induction:** You believe that ...  
 ... rejecting offer was a mistake by Barbara,  
 ... Barbara will choose rationally in the future,  
 ... Barbara believes that you will choose rationally.  
 So, you believe that Barbara chooses 200 or 300.  
 Hence, you will choose price 200.

350, 500

	200	300	400	500
200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250

Barbara



reject

accept

350, 500

**Forward induction:** You believe that ...

... rejecting colleague's offer was a rational choice for Barbara.

So, you believe that Barbara chooses price 400. Hence, you will choose price 300.

	200	300	400	500
200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250

**Barbara**



reject

accept

So, your choice crucially depends on how you revise your belief about Barbara.

Both ways of revising your belief seem plausible.

350, 500



# Conditional beliefs

We would like to model **hierarchies of conditional beliefs**.

That is, we want to model

- the conditional belief that player  $i$  has, at every information set  $h \in H_i$ , about his opponents' **strategy choices**,
- the conditional belief that player  $i$  has, at every information set  $h \in H_i$ , about the **conditional belief** that opponent  $j$  has, at every information set  $h' \in H_j$ , about the opponents' strategy choices,

and so on.

- So, at every information set, a player has a **conditional belief** about the opponents' **strategies** and the opponents' **conditional belief hierarchies**.
- Call a conditional belief hierarchy a **type**.

An **information set** for player  $i$

- is a situation where player  $i$  must make a choice,
- describes the **information** that player  $i$  has about the opponents' **past choices**.

$H_i$ : collection of information sets for player  $i$ .

## Definition (Strategy)

A **strategy** for player  $i$  is a function  $s_i$  that assigns to each of his information sets  $h \in H_i$  some available choice  $s_i(h)$ , **unless**  $h$  cannot be reached due to some choice  $s_i(h')$  at an earlier information set  $h' \in H_i$ .

In the latter case, no choice needs to be specified at  $h$ .

This is different from the **classical** definition of a strategy! It corresponds to **plan of action** in Rubinstein (1991).

## Definition (Epistemic model)

An **epistemic model** for a **dynamic game** specifies for every player  $i$  a set  $T_i$  of possible **types**.

Moreover, it specifies for every type  $t_i \in T_i$ , at every information set  $h \in H_i$ , a **conditional** probabilistic **belief**  $b_i(t_i, h)$  over the set  $S_{-i}(h) \times T_{-i}$  of opponents' **strategy-type** combinations.

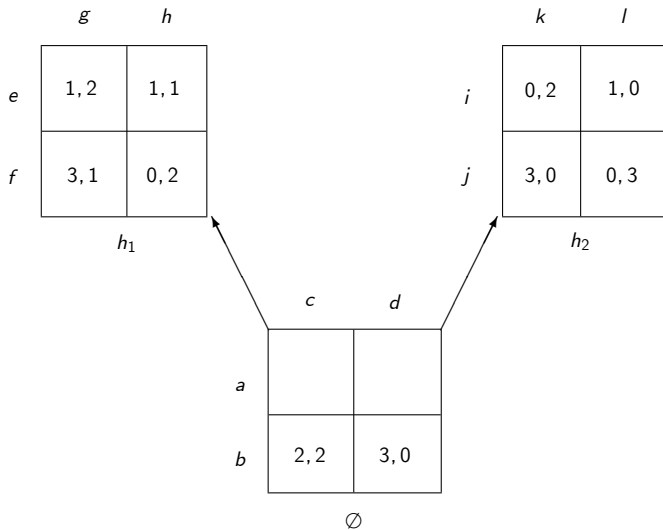
- Here,  $S_{-i}(h)$  is the set of opponents' strategy combinations that make reaching  $h$  possible.
- The epistemic model is based on Ben-Porath (1997) and Battigalli and Siniscalchi (1999).

## Definition (Epistemic model)

An **epistemic model** for a **dynamic game** specifies for every player  $i$  a set  $T_i$  of possible **types**.

Moreover, it specifies for every type  $t_i \in T_i$ , at every information set  $h \in H_i$ , a **conditional** probabilistic **belief**  $b_i(t_i, h)$  over the set  $S_{-i}(h) \times T_{-i}$  of opponents' **strategy-type** combinations.

- From the epistemic model, we can **derive** the **complete belief hierarchy** for every type.
- A type may **revise his belief** about the opponents' **strategies** during the game.
- A type may also **revise his beliefs** about the opponents' **beliefs** during the game.



Types	$T_1 = \{t_1, \hat{t}_1\}, T_2 = \{t_2, \hat{t}_2\}$
<b>Beliefs for player 1</b>	$b_1(t_1, \emptyset) = ((c, h), t_2)$ $b_1(t_1, h_1) = ((c, h), t_2)$ $b_1(t_1, h_2) = ((d, k), \hat{t}_2)$ $b_1(\hat{t}_1, \emptyset) = (0.3) \cdot ((c, g), t_2) + (0.7) \cdot ((d, l), \hat{t}_2)$ $b_1(\hat{t}_1, h_1) = ((c, g), t_2)$ $b_1(\hat{t}_1, h_2) = ((d, l), \hat{t}_2)$
<b>Beliefs for player 2</b>	$b_2(t_2, \emptyset) = (b, t_1)$ $b_2(t_2, h_1) = ((a, f, i), t_1)$ $b_2(t_2, h_2) = ((a, f, i), t_1)$ $b_2(\hat{t}_2, \emptyset) = ((a, e, j), \hat{t}_1)$ $b_2(\hat{t}_2, h_1) = ((a, e, j), \hat{t}_1)$ $b_2(\hat{t}_2, h_2) = ((a, e, j), \hat{t}_1)$

# Common belief in future rationality

You **believe in the opponents' future rationality** if you always believe, throughout the game, that your opponents will make optimal choices at every **present** and **future** information set.

## Definition (Belief in the opponents' rationality)

Type  $t_i$  believes at  $h$  that opponent  $j$  **chooses rationally at  $h'$**  if his conditional belief  $b_i(t_i, h)$  only assigns positive probability to strategy-type pairs  $(s_j, t_j)$  for player  $j$  where strategy  $s_j$  is optimal for type  $t_j$  at information set  $h'$ .

## Definition (Belief in the opponents' future rationality)

Type  $t_i$  believes at  $h$  in opponent  $j$ 's **future** rationality if  $t_i$  believes at  $h$  that  $j$  chooses rationally at every information set  $h'$  for player  $j$  that weakly follows  $h$ .



## Definition (Common belief in future rationality)

(Induction start) Type  $t_i$  expresses **1-fold** belief in future rationality if  $t_i$  believes in the opponents' future rationality.

(Inductive step) For every  $k \geq 2$ , type  $t_i$  expresses  **$k$ -fold** belief in future rationality if  $t_i$  assigns, at every information set  $h \in H_i$ , only positive probability to opponents' types that express  $(k - 1)$ -fold belief in future rationality.

Type  $t_i$  expresses **common belief in future rationality** if  $t_i$  expresses  $k$ -fold belief in future rationality for all  $k$ .

- This concept has been presented in Perea (2014). See Baltag, Smets and Svesper (2009) and Penta (2009) for closely related conditions.
- It represents a **backward induction** type of reasoning: Players only think about the future.

## Definition (Common belief in future rationality)

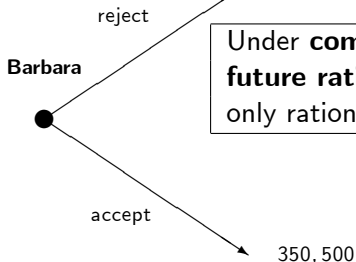
(Induction start) Type  $t_i$  expresses **1-fold** belief in future rationality if  $t_i$  believes in the opponents' future rationality.

(Inductive step) For every  $k \geq 2$ , type  $t_i$  expresses  **$k$ -fold** belief in future rationality if  $t_i$  assigns, at every information set  $h \in H_i$ , only positive probability to opponents' types that express  $(k - 1)$ -fold belief in future rationality.

Type  $t_i$  expresses **common belief in future rationality** if  $t_i$  expresses  $k$ -fold belief in future rationality for all  $k$ .

- Is implicitly present in **subgame perfect equilibrium** (Selten (1965)) and **sequential equilibrium** (Kreps and Wilson (1982)).
- But these concepts, like Nash equilibrium, assume that a player always believes that his opponents are **correct about his beliefs**.

	200	300	400	500
200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250



Under **common belief in future rationality** you can only rationally choose 200.

200	100, 100	200, 0	200, 0	200, 0
300	0, 200	150, 150	300, 0	300, 0
400	0, 200	0, 300	200, 200	400, 0
500	0, 200	0, 300	0, 400	250, 250

Barbara



reject

accept

Types	$T_1 = \{t_1\}, T_2 = \{t_2\}$
Beliefs for Barbara	$b_1(t_1, \emptyset) = (200, t_2)$ $b_1(t_1, h_1) = (200, t_2)$
Beliefs for you	$b_2(t_2, h_1) = ((\text{reject}, 200), t_1)$

350, 500

Both types express **common belief in future rationality**.

- We wish to find those strategies that you can rationally choose under **common belief in future rationality**.
- Can we construct an **algorithm** that helps us find these strategies?
- Yes! It will proceed by iteratedly removing strategies at the various information sets in the game.

## Step 1: 1-fold belief in future rationality.

- Which strategies can player  $i$  rationally choose if he expresses **1-fold belief in future rationality**? That is, if he believes in the opponents' future rationality?
- Consider a type  $t_i$  that believes in the opponents' future rationality. Then,  $t_i$  believes at every information set  $h \in H_i$  that opponent  $j$  chooses optimally at every information set  $h' \in H_j$  that **weakly follows**  $h$ .
- A strategy  $s_j$  for player  $j$  is **optimal** at  $h'$  for some conditional belief at  $h'$ , if and only if,  $s_j$  is **not strictly dominated** within the **full decision problem**  $\Gamma^0(h') = (S_j(h'), S_{-j}(h'))$  at  $h'$ .
- So,  $t_i$  assigns at  $h$  only positive probability to  $j$ 's strategies  $s_j$  that are not strictly dominated within any full decision problem  $\Gamma^0(h')$  that weakly follows  $h$ , and at which  $j$  is active.

## Step 1: 1-fold belief in future rationality.

- So,  $t_i$  assigns at  $h$  only positive probability to  $j$ 's strategies  $s_j$  that are not strictly dominated within any full decision problem  $\Gamma^0(h')$  that weakly follows  $h$ , and at which  $j$  is active.
- At every information set  $h \in H_i$ , delete from the full decision problem  $\Gamma^0(h)$  those strategies  $s_j$  that are **strictly dominated** within some full decision problem  $\Gamma^0(h')$  that **weakly follows**  $h$ , and at which  $j$  is active. This gives the **reduced decision problem**  $\Gamma^1(h)$ .
- Hence, type  $t_i$  assigns at every information set  $h \in H_i$  only positive probability to opponents' strategies in  $\Gamma^1(h)$ .
- So, every strategy that is optimal for  $t_i$  at  $h$ , must **not** be **strictly dominated** within the **reduced decision problem**  $\Gamma^1(h)$ .

## Step 1: 1-fold belief in future rationality.

- So, every strategy that is optimal for  $t_i$  at  $h$ , must **not** be **strictly dominated** within the **reduced decision problem**  $\Gamma^1(h)$ .
- Let  $\Gamma^2(\emptyset)$  be reduced decision problem at  $\emptyset$  which is obtained by eliminating, for every player  $i$ , those strategies that are strictly dominated within some reduced decision problem  $\Gamma^1(h)$  at which  $i$  is active.
- **Conclusion:** Every strategy  $s_i$  that is optimal for some type  $t_i$  which expresses **1-fold** belief in future rationality, must be in  $\Gamma^2(\emptyset)$ .



## Step 2: Up to 2-fold belief in future rationality.

- Which strategies can player  $i$  rationally choose if he expresses **up to 2-fold belief** in future rationality?
- Consider a type  $t_i$  that expresses up to 2-fold belief in future rationality. Then,  $t_i$  assigns at every  $h \in H_i$  only positive probability to opponents' strategy-type pairs  $(s_j, t_j)$  where  $s_j$  is optimal for  $t_j$  at every  $h' \in H_j$  that weakly follows  $h$ , and  $t_j$  expresses 1-fold belief in future rationality.
- We know from Step 1 that every such type  $t_j$  assigns at every  $h' \in H_j$  only positive probability to opponents' strategies in  $\Gamma^1(h')$ .
- So, every such strategy  $s_j$  above must at every  $h' \in H_j$  weakly following  $h$  not be strictly dominated within  $\Gamma^1(h')$ .

## Step 2: Up to 2-fold belief in future rationality.

- So, every such strategy  $s_j$  above must at every  $h' \in H_j$  weakly following  $h$  not be strictly dominated within  $\Gamma^1(h')$ .
- Let  $\Gamma^2(h)$  be the reduced decision problem at  $h$  which is obtained from  $\Gamma^1(h)$  by removing all strategies  $s_j$  which are strictly dominated within some  $\Gamma^1(h')$  weakly following  $h$ , at which  $j$  is active.
- Then, type  $t_i$  will assign at  $h$  only positive probability to strategies  $s_j$  in  $\Gamma^2(h)$ .
- So, every strategy  $s_j$  which is optimal for  $t_i$  at  $h$  must **not be strictly dominated** within  $\Gamma^2(h)$ .

## Step 2: Up to 2-fold belief in future rationality.

- So, every strategy  $s_i$  which is optimal for  $t_i$  at  $h$  must **not** be **strictly dominated** within  $\Gamma^2(h)$ .
- Let  $\Gamma^3(\emptyset)$  be reduced decision problem at  $\emptyset$  which is obtained by eliminating, for every player  $i$ , those strategies that are strictly dominated within some reduced decision problem  $\Gamma^2(h)$  at which  $i$  is active.
- **Conclusion:** Every strategy  $s_i$  that is optimal for some type  $t_i$  which expresses **up to 2-fold** belief in future rationality, must be in  $\Gamma^3(\emptyset)$ .

Fix an information set  $h$  for player  $i$ .

- The **full decision problem** for player  $i$  at  $h$  is  $\Gamma^0(h) = (S_i(h), S_{-i}(h))$ , where  $S_i(h)$  is the set of strategies for player  $i$  that make reaching  $h$  possible, and  $S_{-i}(h)$  is the set of opponents' strategy combinations that make reaching  $h$  possible.
- A **reduced decision problem** for player  $i$  at  $h$  is  $\Gamma(h) = (D_i(h), D_{-i}(h))$ , where  $D_i(h) \subseteq S_i(h)$  and  $D_{-i}(h) \subseteq S_{-i}(h)$ .

## Algorithm (Backward dominance procedure)

*(Induction start) Let  $\Gamma^0(h)$  be the full decision problem at  $h$  for every information set  $h$ .*

*(Inductive step) Let  $k \geq 1$ . At every reduced decision problem  $\Gamma^{k-1}(h)$ , eliminate for every player  $i$  those strategies that are strictly dominated at some reduced decision problem  $\Gamma^{k-1}(h')$  that weakly follows  $h$  and at which player  $i$  is active. This leads to new reduced decision problems  $\Gamma^k(h)$  at every information set.*

- Algorithm is taken from Perea (2014). Similar procedures can be found in Penta (2009) and Chen and Micali (2011).
- The algorithm always **stops within finitely many steps**.
- At every information set, it yields a nonempty set of strategies for every player.

## Theorem (Perea (2014))

(1) For every  $k \geq 1$ , the strategies that can rationally be chosen by a type that expresses **up to  $k$ -fold belief in future rationality** are exactly the strategies that survive the **first  $k + 1$  steps** of the backward dominance procedure at  $\emptyset$ .

(2) The strategies that can rationally be chosen by a type that expresses **common belief in future rationality** are exactly the strategies that survive the **full** backward dominance procedure at  $\emptyset$ .

- A strategy survives the first  $k + 1$  steps of the backward dominance procedure at  $\emptyset$  if it is in the reduced decision problem  $\Gamma^{k+1}(\emptyset)$ .
- A strategy survives the full backward dominance procedure at  $\emptyset$  if it is in the reduced decision problem  $\Gamma^k(\emptyset)$  for every  $k$ .

$\Gamma^0(h_1)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

**Step 1**

$\Gamma^0(h_1)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

## Step 1



$\Gamma^0(h_1)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

**Step 1**

$\Gamma^0(h_1)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
$(r, 500)$	0, 200	0, 300	0, 400	250, 250

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

**Step 1**

$\Gamma^0(h_1)$	200	300	400	500
$(r, 200)$	100, 100	200, 0	200, 0	200, 0
$(r, 300)$	0, 200	150, 150	300, 0	300, 0
$(r, 400)$	0, 200	0, 300	200, 200	400, 0

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

## Step 1

$\Gamma^0(h_1)$	200	300	400	
$(r, 200)$	100, 100	200, 0	200, 0	
$(r, 300)$	0, 200	150, 150	300, 0	
$(r, 400)$	0, 200	0, 300	200, 200	

**B**

reject

accept

$\Gamma^0(\emptyset)$	200	300	400	500
$(r, 400)$	0, 200	0, 300	200, 200	400, 0
<i>accept</i>	350, 500	350, 500	350, 500	350, 500

350, 500

## Step 1

$\Gamma^1(h_1)$	200	300	400	
$(r, 200)$	100, 100	200, 0	200, 0	
$(r, 300)$	0, 200	150, 150	300, 0	
$(r, 400)$	0, 200	0, 300	200, 200	

**B**

reject

accept

$\Gamma^1(\emptyset)$	200	300	400
$(r, 400)$	0, 200	0, 300	200, 200
<i>accept</i>	350, 500	350, 500	350, 500

350, 500

**End of Step 1**

$\Gamma^1(h_1)$       200      300      400

$(r, 200)$	100, 100	200, 0	200, 0	
$(r, 300)$	0, 200	150, 150	300, 0	
$(r, 400)$	0, 200	0, 300	200, 200	

**B**

reject

accept

$\Gamma^1(\emptyset)$	200	300	400
<i>accept</i>	350, 500	350, 500	350, 500

350, 500

**Step 2**

$\Gamma^1(h_1)$       200      300      400

$(r, 200)$	100, 100	200, 0	200, 0	
$(r, 300)$	0, 200	150, 150	300, 0	

**B**

reject

accept

$\Gamma^1(\emptyset)$	200	300	400
<i>accept</i>	350, 500	350, 500	350, 500

350, 500

**Step 2**

$\Gamma^1(h_1)$       200      300

$(r, 200)$	100, 100	200, 0		
$(r, 300)$	0, 200	150, 150		

**B**

reject

accept

$\Gamma^1(\emptyset)$	200	300	400
<i>accept</i>	350, 500	350, 500	350, 500

350, 500

## Step 2



$\Gamma^2(h_1)$       200      300

$(r, 200)$	100, 100	200, 0		
$(r, 300)$	0, 200	150, 150		

**B**

reject

accept

$\Gamma^2(\emptyset)$	200	300
<i>accept</i>	350, 500	350, 500

350, 500

**End of Step 2**

$\Gamma^2(h_1)$       200      300

$(r, 200)$

100, 100	200, 0		

**B**

reject

accept

$\Gamma^2(\emptyset)$	200	300
<i>accept</i>	350, 500	350, 500

350, 500

**Step 3**

$\Gamma^2(h_1)$       200

$(r, 200)$

100, 100			

**B**

reject

accept

$\Gamma^2(\emptyset)$	200	300
<i>accept</i>	350, 500	350, 500

350, 500

**Step 3**

$\Gamma^3(h_1)$       200

$(r, 200)$

100, 100			

**B**

reject

accept

$\Gamma^3(\emptyset)$	200
<i>accept</i>	350, 500

350, 500

**End of algorithm**

## Algorithm (Backward dominance procedure)

*(Induction start) Let  $\Gamma^0(h)$  be the full decision problem at  $h$  for every information set  $h$ .*

*(Inductive step) Let  $k \geq 1$ . At every reduced decision problem  $\Gamma^{k-1}(h)$ , eliminate for every player  $i$  those strategies that are strictly dominated at some reduced decision problem  $\Gamma^{k-1}(h')$  that weakly follows  $h$  and at which player  $i$  is active. This leads to new reduced decision problems  $\Gamma^k(h)$  at every information set.*

- The **order** in which we eliminate strategies – including the order in which we walk through the information sets – is **not important** for the final result!
- In dynamic games with **perfect information**, it coincides with **backward induction procedure** (not due to Zermelo (1913) !).

## Theorem (Common belief in future rationality leads to backward induction)

Consider a dynamic game with **perfect information**.

Then, the strategies that can rationally be chosen under **common belief in future rationality** are exactly the **backward induction strategies**.







- If the game with perfect information is **generic** – that is, all utilities at the terminal histories are different – then there is a **unique** backward induction strategy for every player.
- In **non-generic** games with perfect information, there may be more than one backward induction strategy for a player.

## Theorem (Common belief in future rationality leads to backward induction)







Consider a dynamic game with **perfect information**.







Then, the strategies that can rationally be chosen under **common belief in future rationality** are exactly the **backward induction strategies**.







- So, common belief in future rationality can be seen as an **epistemic foundation for backward induction**.
- **Other epistemic foundations for backward induction** can be found in Aumann (1995), Samet (1996), Balkenborg and Winter (1997), Stalnaker (1998), Asheim (2002), Quesada (2002, 2003), Clausang (2003, 2004), Asheim and Perea (2005), Feinberg (2005), Perea (2008), Baltag, Smets and Zvesper (2009) and Bach and Heilmann (2011).
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